# Application of Group Analysis to Delay Differential Equation 

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#### Abstract

In this paper, Lie group analysis is applied to delay differential equations. It is shown method for constructing and solving determining equations and it is given example.


## INTRODUCTION

Delay differential equations (DDEs) play a central role in many mathematical modelings. Unfortunately, most methods for solving particular types of DDEs come from the approach of trial and error. In this paper, Lie group analysis method, the powerful method [1], is applied to DDEs for finding symmetries. The sketch process is not different from the classical one.

The equations to be studied are ${ }^{1}$

$$
\begin{equation*}
x^{\prime}=F\left(t, x_{t}\right), \tag{1}
\end{equation*}
$$

where, for given $t \in\left[t_{0}, \beta\right)$ and given any function $\chi:[\gamma, t] \rightarrow D$,

$$
F\left(t, \chi_{t}\right) \equiv f\left(t, \chi\left(g_{1}(t)\right), \ldots, \chi\left(g_{m}(t)\right)\right)
$$

$D$ is an open subset in $\mathbb{R}^{n}, x$ and $f$ are $n$-vector-valued enough time differentiable functions, $f:\left[t_{0}, \beta\right) \times D^{m} \rightarrow \mathbb{R}^{n}$, and for each $j=1, \ldots, m, \gamma \leq g_{j}(t) \leq t$ for $t_{0} \leq t \leq \beta$.
Definition 1. A solution of equations (1), with initial condition $\theta(t)$ defined on $\left[\gamma, t_{0}\right]$, is a continuous function $x:\left[\gamma, \beta_{1}\right] \rightarrow D$, for some $\beta_{1} \in\left(t_{0}, \beta\right]$ such that

1. $x(t)=\theta(t)$ for $\gamma \leq t \leq t_{0}$, and
2. $x^{\prime}(t)=F\left(t, x_{t}\right)$ for $t_{0} \leq t \leq \beta_{1}$.

Remark. We understand $x^{\prime}\left(t_{0}\right)$ to mean the right-hand derivative.

[^0]Nonlinear Acoustics at the Beginning of the 21st Century
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Definition 2. We define a symmetry group admitted by DDEs (1) according to Lie's definition of a symmetry group admitted by an equation ${ }^{2}$, i.e., it is a group of transformations which transform a solution of DDEs to a solution of the same system.

The plan of the paper is as follows. The next section provides description of constructing and solving determining equations. Then it is given an example.

## DETERMINING EQUATIONS OF DDEs

## Constructing of Determining Equations

Like the classical method, we will let the symmetry group $G$ of transformations $T_{a}$ :

$$
\bar{t}=T^{t}(t, x ; a), \bar{x}=T^{x}(t, x ; a),
$$

depending on a real parameter $a, t \equiv T^{t}(t, x ; 0)$ and $x \equiv T^{x}(t, x ; 0)$, be admitted by DDEs (1). Suppose $x=\chi(t)$ be a solution, we relate this solution with $\bar{\chi}(\bar{t})$ by $\bar{t}=T^{t}(t, \chi(t) ; a)$ and $\bar{x}=T^{x}(t, \chi(t) ; a)$. In order to write $\bar{x}$ as a function of $\bar{t}$, we first have to derive

$$
\begin{equation*}
t=\psi(\bar{t} ; a) \tag{2}
\end{equation*}
$$

from $\bar{t}=T^{t}(t, \chi(t) ; a)$. Compared with ODEs, in order to consider DDEs' solutions, one has to consider functions not only of a neighborhood of an initial point, but of initial interval $\left[\gamma, t_{0}\right]$ and a neighborhood of $t_{0}$. Local inverse function theorem is not enough to guarantee obtaining (2), we have to require "global inverse function theorem".

We can write down $\bar{x}$ as a function of $\bar{t}$ by $\bar{x}=\bar{\chi}(\bar{t})=T^{x}(\psi(\bar{t} ; a), \chi(\psi(\bar{t} ; a)) ; a)$. So

$$
\bar{x}^{\prime}=\frac{d \bar{\chi}(\bar{t})}{d \bar{t}}=\left(T,{ }_{1}^{x}+T,{ }_{2}^{x} \chi^{\prime}(\psi(\bar{t} ; a))\right) \frac{\partial \psi(\bar{t} ; a)}{\partial \bar{t}}
$$

here $f,{ }_{i}$ means the partial derivative of $f$ with respect to $i$-th argument, and

$$
F\left(\bar{t}, \bar{x}_{\bar{t}}\right)=f\left(\bar{t}, T^{x}\left(\psi\left(g_{1}(\bar{t}) ; a\right), \chi\left(\psi\left(g_{1}(\bar{t}) ; a\right)\right) ; a\right), \ldots, T^{x}\left(\psi\left(g_{m}(\bar{t}) ; a\right), \chi\left(\psi\left(g_{m}(\bar{t}) ; a\right)\right) ; a\right) .\right.
$$

Let $\Xi\left(t, x_{t}, x^{\prime}\right)=x^{\prime}-F\left(t, x_{t}\right)$, then

$$
\begin{equation*}
\Xi\left(t, x_{t}, x^{\prime}\right) \equiv 0 \tag{3}
\end{equation*}
$$

for $x=\chi(t)$ and $t$ in some considered interval, and also $\Xi\left(\bar{t}, \bar{x}_{\bar{t}}, \bar{x}^{\prime}\right) \equiv 0$ :

$$
\begin{equation*}
\left.\frac{\partial \Xi\left(\bar{t}, \bar{x}_{\bar{t}}, \bar{x}^{\prime}\right)}{\partial a}\right|_{a=0}=0 \tag{4}
\end{equation*}
$$

Definition 3. The equations

$$
\begin{equation*}
\left.\frac{\partial \Xi\left(\bar{t}, \bar{x}_{\bar{t}}, \bar{x}^{\prime}\right)}{\partial a}\right|_{a=0,(3)}=0 \tag{5}
\end{equation*}
$$

are called determining equations.

[^1]
## Solving Determining Equations

Let $\xi(t, x)=\left.\frac{\partial T^{t}(t, x ; a)}{\partial a}\right|_{a=0}$ and $\eta(t, x)=\left.\frac{\partial T^{x}(t, x ; a)}{\partial a}\right|_{a=0}$. From the previous section, we obtain

$$
\begin{align*}
\left.\frac{\partial \bar{\chi}^{\prime}(\bar{t})}{\partial a}\right|_{a=0}= & \eta_{, 1}(t, \chi(t))+(\eta, 2(t, \chi(t))-  \tag{6}\\
& \left.\xi_{, 1}(t, \chi(t))\right) \chi^{\prime}(t)-\xi_{, 2}(t, \chi(t))\left[\chi^{\prime}(t)\right]^{2}-\xi(t, \chi(t)) \chi^{\prime \prime}(t), \\
\left.\frac{\partial \bar{\chi}\left(g_{\lambda}(\bar{t})\right)}{\partial a}\right|_{a=0}= & -\xi\left(g_{\lambda}(t), \chi\left(g_{\lambda}(t)\right)\right) \chi^{\prime}\left(g_{\lambda}(t)\right)+\eta\left(g_{\lambda}(t), \chi\left(g_{\lambda}(t)\right)\right) .
\end{align*}
$$

Let $\Delta$ and $\Theta_{\lambda}$ denote the right side terms of equations (6) respectively. Equations (4) become

$$
\begin{equation*}
\sum_{\lambda=1}^{m} \Xi, \lambda_{\lambda+1}\left(t, x_{t}, x^{\prime}\right) \Theta_{\lambda}+\Xi,_{m+2} \Delta=0 \tag{7}
\end{equation*}
$$

To solve determining equations, we have to consider (7) on the manifold (3). Then the involved variable and functions are:

- $\quad t, \chi(t), \chi\left(g_{\lambda}(t)\right), \chi^{\prime}\left(g_{\lambda}(t)\right), \chi^{\prime \prime}\left(g_{\lambda}(t)\right), \ldots$
- functions $\eta$ and $\xi$ of $(t, \chi(t))$ or of $\left(g_{\lambda}(t), \chi\left(g_{\lambda}(t)\right)\right)$ and their derivatives $\eta_{, 1}, \xi_{, 1}, \eta_{, 2}, \xi_{, 2}, \ldots$
where $\lambda=1, \ldots, m$.
Determining equations (5) have to be satisfied identically for any $t$ in a neighborhood of $t_{0}, t \geq t_{0}$, and for any solution $\chi(t)$ of equations (1). For any initial function $\theta(t), t \in\left[\gamma, t_{0}\right]$, existence theory [2] guarantees existence of solution $\chi(t)$, therefore, by arbitrariness of $t \in\left[\gamma, \beta_{1}\right]$ and initial function $\theta(t)$, the determining equations can be split into a system of several equations and can be solved analytically, as it is done for ODEs [4].


## Example

Let us consider

$$
\begin{gather*}
x^{\prime \prime}(t)-x(t)+x(t-r)=0,  \tag{8}\\
x^{\prime}\left(t_{0}\right)=x_{1}, \quad x(s)=\theta(s), \quad s \in\left[t_{0}-r, t_{0}\right], r>0 .
\end{gather*}
$$

The determining equation for equation (7) is

$$
\begin{gathered}
\eta, 11_{1}(t, \chi(t))+\chi^{\prime}(t)\left(2 \eta, 12(t, \chi(t))-\xi_{, 11}(t, \chi(t))\right)+ \\
{\left[\chi^{\prime}(t)\right]^{2}\left(\eta, 22(t, \chi(t))-2 \xi_{, 2}(t, \chi(t))\right)-\left[\chi^{\prime}(t)\right] \xi, 22(t, \chi(t))+} \\
{[\chi(t)-\chi(t-r)]\left(\eta, 2(t, \chi(t))-2 \xi_{, 1}(t, \chi(t))\right)-3\left[\chi^{\prime}(t)(x(t)-x(t-r))\right] \xi_{, 2}(t, \chi(t))-} \\
\xi(t, \chi(t))\left(\chi^{\prime}(t)-\chi^{\prime}(t-r)\right)+\xi(t, \chi(t)) \chi^{\prime}(t)-\eta(t, \chi(t))- \\
\xi(t-r, \chi(t-r)) \chi^{\prime}(t-r)+\eta(t-r, \chi(t-r))=0
\end{gathered}
$$

The generator obtained from solving the determining equation is

$$
X=h(t) \partial_{t}+c_{1} x \partial x,
$$

where $c_{1}$ is an arbitrary constant and the function $h(t)$ is an arbitrary solution of equation (8).

## CONCLUSION

In the strength of the theory of existence of solution of the problem for DDEs, the process of solving determining equations for DDEs is similar to obtaining solutions of determining equations for differential equations.

In this paper, it is shown that Lie group analysis can be applied to DDEs. And it can also be applied to other types of DEs, like integro-differential equations, functional differential equations, etc.

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[^0]:    ${ }^{1}$ See, for example, in [2]

[^1]:    ${ }^{2}$ See p.101, section 1, chapter 6 in [3]

